

AMENDMENTS TO THE SPECIFICATION:

Please replace the paragraph beginning at page 2, line 27, with the following rewritten paragraph:

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--The device shown in the drawings incorporates a conveyor 1 on which are carried (for example) individual food trays 2 which are to be inserted into open ended cartons 3. As the conveyor 1 moves (from right to left as shown in FIG. 1) the cartons 3 move at the same speed with the conveyor. A robotic support body 4 incorporates a control mechanism arranged to move the support body about suitable rotational axes so as to cause a control arm 5 to be moved across the conveyor 1. The arm 5 incorporates paddles 6 which engage with the trays 2 so as to push the trays towards the cartons 3. The arm 5 is moved across the conveyor 1, but at the same time moves from right to left at the same speed as for the conveyor 1. The diagonal path taken by a head 9 of the support body, carrying the arm 5, is indicated by the broken line 7 as shown in FIGS. 2 and 3. This results in the trays 2 being pushed fully home into the cartons 3. As seen in the drawings, conveyor 1 has upward projections 1' perpendicular to the length of conveyor 1, that define between them paths 1'' also perpendicular to the length of conveyor 1, along which paths the trays 2 are pushed by arm 5 into cartons 3. The arm 5 is then raised and the head 9 is brought back along the reciprocal path 8 (as shown in FIG. 4) until the arm returns to and is lowered into

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the start condition as shown in FIG. 1. The same operation can
then be employed to move another set of four trays into a
subsequent series of four cartons.--
